



Supplementary materials for

Na PANG, Dawei ZHANG, Shuqian ZHU, 2024. Asynchronous gain-scheduled control of deepwater drilling riser system with hybrid event-triggered sampling and unreliable communication. *Front Inform Technol Electron Eng*, 25(2):272-285. <https://doi.org/10.1631/FITEE.2300625>

1 Proof of Theorem 1

Proof For the system (Eqs. (10) and (11)), we construct the discontinuous Lyapunov–Krasovskii functional (LKF) as follows:

$$\begin{aligned} \mathcal{V}(t) = & \eta_1^T(t)P\eta_1(t) + \int_{t-\eta_M}^t z^T(s)Qz(s)ds + \int_{-\eta_M}^0 \int_{t+s}^t \dot{z}^T(\theta)R\dot{z}(\theta)d\theta ds + (\eta_M - \tau(t)) \int_{t-\bar{\tau}(t)}^t \eta_2^T(s)S\eta_2(s)ds \\ & + \tau(t)\nu_k^T(t - \tau(t))G_2\nu_k(t - \tau(t)) + h \int_{t-\tau(t)}^t \dot{z}^T(s)G_3\dot{z}(s)ds + d^T(t)G_1d(t) \end{aligned}$$

for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), where $P > 0, Q > 0, R > 0, S > 0, G_i > 0$ ($i = 1, 2, 3$), $\bar{\tau}(t) = \tau(t) - \tau_{t_k+i}$, $\eta_1(t) = \text{col}\{z(t), \int_{t-\eta_M}^t z(s)ds\}$, and $\eta_2(s) = \text{col}\{\dot{z}(s), z(s - \tau(s)), z(s - \bar{\tau}(s))\}$.

(1) We show that $\mathcal{V}(t)$ satisfies

$$\mathbb{E}\{\mathcal{V}(t^-) - \mathcal{V}(t)\} > 0, \quad i = 1, 2, \dots, \mathcal{J}_k, \quad (\text{S1})$$

$$\mathbb{E}\{\mathcal{V}(t^-) - \mathcal{V}(t) - \omega d^T(t^-)Wd(t^-)\} > 0, \quad i = 0, \quad (\text{S2})$$

for $t \in \{f_{t_k+i}\}$ ($\forall k \in \mathbb{N}$).

For $t = f_{t_k+i}$ ($i = 1, 2, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), one has

$$\mathbb{E}\{\mathcal{V}(t^-) - \mathcal{V}(t)\} \geq \xi_1^T(t)\Theta_1\xi_1(t),$$

where

$$\xi_1(t) = \begin{bmatrix} z((t_k + i - 1)h) - z(t_k h) \\ z((t_k + i)h) - z(t_k h) \end{bmatrix} \text{ and } \Theta_1 = \begin{bmatrix} G_3 + (h + \tau_{t_k+i})G_2 & -G_3 \\ -G_3 & G_3 - \tau_{t_k+i}T_2 \end{bmatrix}.$$

For $t = f_{t_k}$ ($\forall k \in \mathbb{N}$), one has

$$\begin{aligned} & \mathbb{E}\{\mathcal{V}(t^-) - \mathcal{V}(t) - \omega d^T(t^-)Wd(t^-)\} \\ = & d^T(t^-)G_1d(t^-) - \omega d^T(t^-)Wd(t^-) + h \int_{(t_k-1)h}^{t_k h} \dot{z}^T(s)G_3\dot{z}(s)ds - d^T(t)G_1d(t) \\ & + (h + \tau_{t_k})(z((t_k - 1)h) - z(t_{k-1}h))^T G_2(z((t_k - 1)h) - z(t_{k-1}h)). \end{aligned} \quad (\text{S3})$$

It can be derived from Eqs. (11) and (S3) that

$$\mathbb{E}\{\mathcal{V}(t^-) - \mathcal{V}(t) - \omega d^T(t^-)Wd(t^-)\} \geq \xi_2^T(t)\Theta_2\xi_2(t),$$

where

$$\xi_2(t) = \begin{bmatrix} d(t^-) \\ z(t_{k-1}h) - z(t_k h) \\ z((t_k - 1)h) - z(t_{k-1}h) \end{bmatrix} \text{ and } \Theta_2 = \begin{bmatrix} \Pi_3^{(1,1)} & \Pi_3^{(1,2)} \\ \star & G_3 + (h + \tau_{t_k})G_2 \end{bmatrix}.$$

Since Θ_1 and Θ_2 are convex on $\tau_{t_k+i} \in [0, \tau_M]$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), conditions (S1) and (S2) can be ensured when condition (16) is satisfied.

(2) We prove that

$$\mathbb{E} \{ \mathcal{L}\mathcal{V}(t) - d^\top(t)Wd(t) \} < 0 \quad (\text{S4})$$

holds for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), where the infinitesimal operator \mathcal{L} is defined as

$$\mathcal{L}\mathcal{V}(t) = \lim_{\Delta t \rightarrow 0^+} \Delta t^{-1} \{ \mathbb{E} \{ \mathcal{V}(t + \Delta t) \mid t \} - \mathcal{V}(t) \}. \quad (\text{S5})$$

Using Eq. (S5), one obtains

$$\begin{aligned} & \mathcal{L}\mathcal{V}(t) - d^\top(t)Wd(t) \\ &= \vartheta^\top(t) (\Psi_0 + \tau(t)\Psi_1 + \tau_{t_k+i}\Psi_2) \vartheta(t) - \int_{t-\bar{\tau}(t)}^t \dot{z}^\top(s)R_s \dot{z}(s) ds - \int_{t-\eta_M}^{t-\bar{\tau}(t)} \dot{z}^\top(s)R \dot{z}(s) ds, \end{aligned} \quad (\text{S6})$$

where

$$\begin{aligned} \vartheta(t) &= \text{col} \{ \vartheta_1(t), \vartheta_2(t) \}, \\ \vartheta_1(t) &= \text{col} \{ z(t), \dot{z}(t), z(t - \tau(t)), \nu_k(t - \tau(t)), z(t - \eta_M) \}, \\ \vartheta_2(t) &= \text{col} \left\{ z(t - \bar{\tau}(t)), \int_{t-\bar{\tau}(t)}^t \frac{z(s)}{\bar{\tau}(t)} ds, \int_{t-\tau(t)}^{t-\bar{\tau}(t)} \frac{z(s)}{\tau_{t_k+i}} ds, \int_{t-\eta_M}^{t-\tau(t)} \frac{z(s)}{\eta_M - \tau(t)} ds, d(t) \right\}. \end{aligned}$$

Using Corollary 2 in Zhang et al. (2018) to the integral terms in Eq. (S6) yields

$$\begin{aligned} & - \int_{t-\bar{\tau}(t)}^t \dot{z}^\top(s)R_s \dot{z}(s) ds - \int_{t-\eta_M}^{t-\bar{\tau}(t)} \dot{z}^\top(s)R \dot{z}(s) ds \\ & \leq \vartheta^\top(t) \left[\tau_{t_k+i} U_2 \text{diag} \{ R^{-1}, (3R)^{-1} \} U_2^\top + \text{Sym} \{ U_1 \Gamma \varphi_7 + U_2 \Gamma \varphi_8 + U_3 \Gamma \varphi_{10} \} \right. \\ & \quad \left. + (\tau(t) - \tau_{t_k+i}) U_1 \text{diag} \{ R_s^{-1}, (3R_s)^{-1} \} U_1^\top + (\eta_M - \tau(t)) U_3 \text{diag} \{ R^{-1}, (3R)^{-1} \} U_3^\top \right] \vartheta(t). \end{aligned} \quad (\text{S7})$$

For system (10) with $h(t) = 0$, there exist two arbitrary matrices X_1 and X_2 such that

$$\sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^\top(t) (\epsilon_1^\top X_1 + \epsilon_2^\top X_2) [A_i \epsilon_1 + BK_j (\epsilon_3 - \epsilon_4 + (1 - \beta) \epsilon_{10}) - \epsilon_2] \vartheta(t) = 0. \quad (\text{S8})$$

It is derived from condition (12) that

$$\vartheta^\top(t) [\epsilon_4^\top \bar{T} \epsilon_4 - \sigma^2 (\epsilon_3 - \epsilon_4)^\top \bar{T} (\epsilon_3 - \epsilon_4)] \vartheta(t) \leq 0. \quad (\text{S9})$$

From conditions (S6)–(S8), one can further derive that

$$\mathcal{L}\mathcal{V}(t) - d^\top(t)Wd(t) \leq \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^\top(t) \mathcal{E}_{ij}(t) \vartheta(t) < 0$$

holds if and only if there exists a constant $\rho > 0$ such that the following inequality is valid for $T = \rho \bar{T}$ and all nonzero $\vartheta(t)$:

$$\mathcal{L}\mathcal{V}(t) - d^\top(t)Wd(t) \leq \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^\top(t) \bar{\mathcal{E}}_{ij}(t) \vartheta(t) < 0 \quad (\text{S10})$$

for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), where

$$\bar{\mathcal{E}}_{ij}(t) = \mathcal{E}_{ij}(t) - \epsilon_4^\top T \epsilon_4 + \sigma^2 (\epsilon_3 - \epsilon_4)^\top T (\epsilon_3 - \epsilon_4),$$

$$\begin{aligned} \mathcal{E}_{ij}(t) &= \Psi_0 + \eta_M U_3 \text{diag} \{ R^{-1}, (3R)^{-1} \} U_3^\top + \tau(t) (\Psi_1 + U_1 \text{diag} \{ R_s^{-1}, (3R_s)^{-1} \} U_1^\top \\ & \quad - U_3 \text{diag} \{ R^{-1}, (3R)^{-1} \} U_3^\top) + \tau_{t_k+i} (\Psi_2 + U_2 \text{diag} \{ R^{-1}, (3R)^{-1} \} U_2^\top - U_1 \text{diag} \{ R_s^{-1}, (3R_s)^{-1} \} U_1^\top) \\ & \quad + \text{Sym} \{ (\epsilon_1^\top X_1 + \epsilon_2^\top X_2) (A_i \epsilon_1 + BK_j \mathcal{E} - \epsilon_2) \} + \text{Sym} \{ U_1 \Gamma \varphi_7 + U_2 \Gamma \varphi_8 + U_3 \Gamma \varphi_{10} \}. \end{aligned}$$

Furthermore, inequality (S10) is satisfied if there exists a matrix $H < 0$ such that

$$\sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \bar{\mathcal{E}}_{ij}(t) \vartheta(t) - S(t) < 0, \quad (\text{S11})$$

where

$$S(t) = \Sigma^T(t) H \Sigma(t) \text{ and } \Sigma(t) = \begin{bmatrix} \varsigma_1(t) \varphi_{11} \vartheta(t) \\ \varsigma_2(t) \varphi_{11} \vartheta(t) \\ \varsigma_3(t) \varphi_{11} \vartheta(t) \\ \varsigma_1(t - \tau(t)) \varphi_{11} \vartheta(t) \\ \varsigma_2(t - \tau(t)) \varphi_{11} \vartheta(t) \\ \varsigma_3(t - \tau(t)) \varphi_{11} \vartheta(t) \end{bmatrix}.$$

The left side of inequality (S11) can be rewritten as follows:

$$\begin{aligned} & \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \bar{\mathcal{E}}_{ij}(t) \vartheta(t) - S(t) \\ = & \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \left(\bar{\mathcal{E}}_{ij}(t) - \varphi_{11}^T (H^{(i,j+3)} + H^{(j+3,i)}) \varphi_{11} \right) \vartheta(t) \\ & - \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \varphi_{11}^T \left(H^{(i,j)} + H^{(j,i)} + H^{(i+3,j+3)} + H^{(j+3,i+3)} \right) \varphi_{11} \vartheta(t) \\ & - \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) (\varsigma_j(t) - \varsigma_j(t - \tau(t))) \vartheta^T(t) \varphi_{11}^T \left(H^{(i,j)} + H^{(j,i)} \right) \varphi_{11} \vartheta(t) \\ & + \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 (\varsigma_i(t) - \varsigma_i(t - \tau(t))) \varsigma_j(t - \tau(t)) \vartheta^T(t) \varphi_{11}^T \left(H^{(i+3,j+3)} + H^{(j+3,i+3)} \right) \varphi_{11} \vartheta(t). \end{aligned} \quad (\text{S12})$$

For arbitrary symmetric matrices M_i and N_i ($i = 1, 2, 3$), the following equations hold:

$$\sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) (\varsigma_j(t) - \varsigma_j(t - \tau(t))) N_i = 0, \quad (\text{S13})$$

$$\sum_{i=1}^3 \sum_{j=1}^3 (\varsigma_i(t) - \varsigma_i(t - \tau(t))) \varsigma_j(t - \tau(t)) M_j = 0. \quad (\text{S14})$$

If conditions (18) and (19) are satisfied, using Lemma 2, we can derive from Eqs. (S12)–(S14) that

$$\sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \bar{\mathcal{E}}_{ij}(t) \vartheta(t) - S(t) < \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \tilde{\mathcal{E}}_{ij}(t) \vartheta(t), \quad (\text{S15})$$

where $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$) and

$$\begin{aligned} \tilde{\mathcal{E}}_{ij}(t) &= \bar{\Psi}_{ij} + \tau(t) \bar{\Psi}_1 + \tau_{t_k+i} \bar{\Psi}_2, \\ \bar{\Psi}_{ij} &= \Psi_{ij} + \eta_M U_3 \text{diag}\{R^{-1}, (3R)^{-1}\} U_3^T, \\ \bar{\Psi}_1 &= \Psi_1 + U_1 \text{diag}\{R_s^{-1}, (3R_s)^{-1}\} U_1^T - U_3 \text{diag}\{R^{-1}, (3R)^{-1}\} U_3^T, \\ \bar{\Psi}_2 &= \Psi_2 + U_2 \text{diag}\{R^{-1}, (3R)^{-1}\} U_2^T - U_1 \text{diag}\{R_s^{-1}, (3R_s)^{-1}\} U_1^T. \end{aligned}$$

Using Lemma 7 in Zhang and Han (2014) and Lemma 2 in Kim (2016) in relation to $\tilde{\mathcal{E}}_{ij}(t) < 0$ related to $\tau(t) \in [\tau_{t_k+i}, \eta_M]$ for the cases that $\bar{\Psi}_1 \geq 0$ and $\bar{\Psi}_1 < 0$, respectively, one has that $\tilde{\mathcal{E}}_{ij}(t) < 0$ can be ensured

by

$$\bar{\Psi}_{ij} + (\bar{\Psi}_1 + \bar{\Psi}_2)\tau_{t_k+i} < 0, \quad (\text{S16})$$

$$\bar{\Psi}_{ij} + \eta_M \bar{\Psi}_1 + \tau_{t_k+i} \bar{\Psi}_2 < 0. \quad (\text{S17})$$

Using the same methods in relation to conditions (S16) and (S17) that are related to τ_{t_k+i} and the Schur complement, we obtain

$$\sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \vartheta^T(t) \tilde{\mathcal{E}}_{ij}(t) \vartheta(t) < 0 \quad (\text{S18})$$

if condition (17) is satisfied. Combining conditions (S6), (S10), (S11), (S15), and (S18) yields $\mathbb{E}\{\mathcal{L}\mathcal{V}(t) - d^T(t)Wd(t)\} < 0$ for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$).

(3) We prove that the system (Eqs. (10) and (11)) is exponentially mean-square stable with H_∞ performance. Accordingly, we construct an LKF $\tilde{\mathcal{V}}(t) = e^{v_1 t} \mathcal{V}(t)$. Then, calculating $\mathbb{E}\{\mathcal{L}\tilde{\mathcal{V}}(t)\}$ and using condition (S4), we have

$$\mathbb{E}\{\mathcal{L}\tilde{\mathcal{V}}(t)\} = v_1 e^{v_1 t} \mathbb{E}\{\mathcal{V}(t)\} + e^{v_1 t} \mathbb{E}\{\mathcal{L}\mathcal{V}(t)\} \leq v_1 e^{v_1 t} \mathbb{E}\{\mathcal{V}(t)\} + e^{v_1 t} \mathbb{E}\{d^T(t)Wd(t)\}. \quad (\text{S19})$$

Integrating condition (S19) on the interval $[t_0 h, t)$ and using conditions (S1) and (S2) and $t_{k+1}h - t_k h \leq \varkappa$, one has

$$\mathbb{E}\{\mathcal{V}(t) - e^{v_1(t_0 h - t)} \mathcal{V}(t_0 h)\} \leq \int_{t_0 h}^t v_1 e^{v_1(s-t)} \mathbb{E}\{\mathcal{V}(s)\} ds + \omega \mathbb{E}\{d^T(f_{t_k})Wd(f_{t_k})\}. \quad (\text{S20})$$

There exists a constant α for a sufficiently small $v_1 > 0$ such that

$$\mathbb{E}\{\mathcal{V}(t) - \omega d^T(f_{t_k})Wd(f_{t_k})\} \leq \alpha e^{-v_1(t-t_0 h)} \mathbb{E}\{\|z(t_0 h)\|^2 + \|d(t_0 h)\|^2\}. \quad (\text{S21})$$

It is clear from $\mathcal{V}(t)$ and $d^T(t)G_1 d(t) < \mathcal{V}(t)$ that

$$\lambda_{\min}(P) \mathbb{E}\{\|z(t)\|^2\} \leq \mathbb{E}\{\mathcal{V}(t) - d^T(f_{t_k})G_1 d(f_{t_k})\} \quad (\text{S22})$$

and

$$\lambda_{\min}(G_1 - \omega W) \mathbb{E}\{\|d^T(t)\|^2\} \leq \mathbb{E}\{\mathcal{V}(t) - \omega d^T(f_{t_k})Wd(f_{t_k})\} \quad (\text{S23})$$

hold for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$). Since $G_1 - \omega W > 0$ and from conditions (S21)–(S23), one can obtain that

$$\begin{aligned} \mathbb{E}\{\|z(t)\|^2\} &\leq v_2 e^{-v_1(t-t_0 h)} \mathbb{E}\{\|z(t_0 h)\|^2 + \|\eta(t_0 h)\|^2\}, \\ \mathbb{E}\{\|\eta(t)\|^2\} &\leq v_2 e^{-v_1(t-t_0 h)} \mathbb{E}\{\|z(t_0 h)\|^2 + \|\eta(t_0 h)\|^2\}, \end{aligned}$$

where $v_2 = \max\{\alpha/\lambda_{\min}(P), \alpha/\lambda_{\min}(G_1 - \omega W)\}$. Then the system (Eqs. (10) and (11)) subject to condition (12) is exponentially mean-square stable. For any nonzero $h(t)$, we have

$$\begin{aligned} &\mathbb{E}\{\mathcal{L}\mathcal{V}(t) - d^T(t)Wd(t)\} \\ &\leq \sum_{i=1}^3 \sum_{j=1}^3 \varsigma_i(t) \varsigma_j(t - \tau(t)) \begin{bmatrix} \vartheta(t) \\ h(t) \end{bmatrix}^T \begin{bmatrix} \tilde{\mathcal{E}}_{ij}(t) & (\epsilon_1^T X_1 + \epsilon_2^T X_2)D \\ \star & 0 \end{bmatrix} \begin{bmatrix} \vartheta(t) \\ h(t) \end{bmatrix} \\ &\quad + \mathbb{E}\{\eta^T(t)\eta(t)\} - \mathbb{E}\{\eta^T(t)\eta(t)\} + \gamma^2 h^T(t)h(t) - \gamma^2 h^T(t)h(t). \end{aligned}$$

If condition (17) is ensured, it can be derived that

$$\mathbb{E}\{\mathcal{L}\mathcal{V}(t) - d^T(t)Wd(t) + \eta^T(t)\eta(t)\} - h^T(t)h(t) \leq 0 \quad (\text{S24})$$

holds for $t \in \mathcal{F}_{k,i}$ ($i = 0, 1, \dots, \mathcal{J}_k, \forall k \in \mathbb{N}$), and

$$\begin{aligned}
& \int_{t_0h}^{\infty} \mathbb{E}\{\mathcal{L}\mathcal{V}(s) - d^T(s)Wd(s)\}ds \\
& \geq \sum_{k=0}^{\infty} \mathbb{E}\{\mathcal{V}(f_{t_{k+1}}^-) - \mathcal{V}(f_{t_k}) - d^T(f_{t_k})Wd(f_{t_k})\} \\
& \geq \sum_{k=0}^{\infty} \mathbb{E}\{\mathcal{V}(f_{t_{k+1}}) + d^T(f_{t_k})Wd(f_{t_k})\} - \sum_{k=0}^{\infty} \mathbb{E}\{\mathcal{V}(f_{t_k}) + d^T(f_{t_k})Wd(f_{t_k})\} \\
& = \mathbb{E}\{\mathcal{V}(t_{\infty}) - \mathcal{V}(t_0h)\}. \tag{S25}
\end{aligned}$$

Considering $\mathbb{E}\{\mathcal{V}(t_{\infty})\} > 0$ and $\mathbb{E}\{\mathcal{V}(t_0h)\} = 0$ under $z(t_0h) = 0$ and $d(t_0h) = 0$, one can conclude from conditions (S24) and (S25) that $\mathbb{E}\{\|\eta(t)\|_2\} \leq \gamma\|h(t)\|_2$. Combining with the proof in (1)–(3), we complete the proof.

2 Proof of Theorem 2

Proof Let $X = X_1^{-T} = \varrho X_2^{-T}$, $Y_i = K_i X$ ($i = 1, 2, 3$), $\mathcal{X}_1 = \text{diag}\{X, X\}$, $\mathcal{X}_2 = \text{diag}\{X, X, X\}$, $\mathcal{X}_3 = \text{diag}\{X, X, \dots, X\}_{10n \times 10n}$, $\mathcal{X}_4 = \text{diag}\{\mathcal{X}_1, \mathcal{X}_1\}$, $\tilde{P} = \mathcal{X}_1^T P \mathcal{X}_1$, $\tilde{Q} = X^T Q X$, $\tilde{R} = X^T R X$, $\tilde{S} = \mathcal{X}_2^T S \mathcal{X}_2$, $\tilde{T} = X^T T X$, $\tilde{W} = X^T W X$, $\tilde{G}_i = X^T G_i X$, $\tilde{M}_i = \mathcal{X}_2^T M_i \mathcal{X}_2$, $\tilde{N}_i = \mathcal{X}_2^T N_i \mathcal{X}_2$, $\tilde{U}_i = \mathcal{X}_3^T U_i \mathcal{X}_1$ ($i = 1, 2, 3$), $\tilde{\Pi}_1 = \mathcal{X}_1^T \Pi_1 \mathcal{X}_1$, $\tilde{\Pi}_2 = \mathcal{X}_1^T \Pi_2 \mathcal{X}_1$, $\tilde{\Pi}_3 = \mathcal{X}_2^T \Pi_3 \mathcal{X}_2$, and $\tilde{H}^{(i,j)} = \mathcal{X}_2^T H^{(i,j)} \mathcal{X}_2$ ($i, j = 1, 2, \dots, 6$). Then pre- and post-multiplying both sides of Ξ_{lij} ($l = 1, 3$) with $\text{diag}\{\mathcal{X}_3, \mathcal{X}_1, 1\}^T$ and its transpose, and Ξ_{lij} ($l = 2, 4$) with $\text{diag}\{\mathcal{X}_3, \mathcal{X}_4, 1\}^T$ and its transpose, respectively, and using the Schur complement, one can obtain conditions (20)–(23). The proof is completed.

References

- Kim JH, 2016. Further improvement of Jensen inequality and application to stability of time-delayed systems. *Automatica*, 64:121-125. <https://doi.org/10.1016/j.automatica.2015.08.025>
- Zhang XM, Han QL, 2014. Global asymptotic stability analysis for delayed neural networks using a matrix-based quadratic convex approach. *Neur Netw*, 54:57-69. <https://doi.org/10.1016/j.neunet.2014.02.012>
- Zhang XM, Han QL, Zeng ZG, 2018. Hierarchical type stability criteria for delayed neural networks via canonical Bessel–Legendre inequalities. *IEEE Trans Cybern*, 48(5):1660-1671. <https://doi.org/10.1109/TCYB.2017.2776283>