

Analytical solution for upheaval buckling of shallow buried pipelines in inclined cohesionless soil*

Bo HUANG¹, Jing-wen LIU^{1,3}, Ji-ying FAN^{†‡1,2}, Dao-sheng LING¹

¹Institute of Geotechnical Engineering, College of Architectural and Civil Engineering, Zhejiang University, Hangzhou 310058, China

²Geoengineering Centre at Queen's-RMC, Queen's University, Kingston, ON, K7L 3N6, Canada

³Bureau of Housing and Urban-Rural Development of Chengdu, Chengdu 610094, China

[†]E-mail: jiyang.fan@queensu.ca

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Abstract: Upheaval buckling of pipelines can occur under thermal expansion and differential ground settlement. Research on this phenomenon has usually assumed the pipes are buried in horizontal ground. For long-distance transmission pipelines across mountainous areas, the ground surface is commonly inclined. Based on the Rankine earth pressure theory and Mohr-Coulomb failure criterion, analytical formulae for calculating the peak uplift resistance and the slip surface angles for a buried pipe in inclined ground are presented in this paper. Analyses indicate that the slip surfaces in inclined ground are asymmetric and rotate towards the downhill side. Under a shallow burial depth, the failure plane angle is highly impacted by the ground inclination. When the embedment ratio (H/D) is more than 4, the influence of the ground slope on the failure plane angle is negligible. The peak uplift resistance reduces in inclined ground, especially when H/D is less than 1. Finally, a simple equation considering the impact of ground inclination is proposed to predict the peak uplift resistance.

Key words: Shallow buried pipe; Upheaval buckling; Inclined ground; Analytical formulation; Soil deformation mechanism
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1 Introduction


Long-distance pipelines characterized by large diameter, high pressure, and high transport capacity, are used worldwide as one of the most important and economical ways to transport oil and gas. In China, 70% of oil and 99% of natural gas are transported through long-distance pipelines. Since some pipelines have been in service for decades, security issues have been currently receiving increasing attention, espe-

cially in mountainous areas with complicated topography (e.g. mountains, hills, and rugged plateaux).

More than 40% of the Chinese mainland area is classified as mountainous-hilly terrain. According to a survey in the 1990s, the probability of failure for a buried pipeline in the southwestern mountainous areas of China is significantly higher than that in the northern and northeastern plain areas. In eastern areas like Zhejiang province, 70.4% of the land is covered by mountains/hills higher than 200 m. Some pipelines in that area unavoidably traverse through mountainous regions (e.g. the Hangzhou-Zhoushan gas pipelines). Mountainous-hilly areas are usually topographically complex since the ground inclination can exceed 30°; therefore, pipelines are buried underground for protection. Even so, under conditions of thermal expansion and differential ground settlement, upheaval buckling problem arises when the pipeline

[‡] Corresponding author

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 ORCID: Bo HUANG, <https://orcid.org/0000-0002-7293-8618>; Ji-ying FAN, <https://orcid.org/0000-0002-4632-1980>

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is buried in a shallow condition (Hobbs, 1984; Maltby and Calladine, 1995; Saeedzadeh and Hataf, 2011).

The research to date on the upheaval buckling has mostly been focusing on the horizontal ground condition (Bransby et al., 2001; Huang et al., 2014; Chakraborty and Kumar, 2016). According to observations in previous tests, the uplift mechanism involves a sliding block bounded between a pair of shear bands orienting at a inclination angle to the vertical (Cheuk et al., 2008; Huang et al., 2015). The uplift resistance offered by soil is highly dependent on the upward displacement, and generally consists of three components: (1) the submerged effective weight of the pipe, (2) the submerged effective weight of soil being lifted, and (3) the shearing resistance of soil in the vertical direction (Wang et al., 2012). Considering that pipe-soil interaction is influenced by many factors, such as the properties of the soil and pipe, burial depth, velocity of soil movement, and boundary conditions, numerical analysis has also been adopted to study the uplift resistance (Roy et al., 2018a, 2018b). The prepeak increase and postpeak decrease responses of the load-displacement relationship observed in previous tests can be well explained by the strain-hardening and strain-softening behaviours of sand.

For the inclined ground condition, the slip mode and soil resistance for an uplift pipe might be different from those in horizontal ground, as the major principal stress axes rotate with the change of ground inclination (Terzaghi, 1943). The existing design methods for a pipeline based on the horizontal ground assumption may reduce pipeline security and result in failure.

Research on soil-structure interaction in inclined ground began in 1943, when Terzaghi (1943) presented a graphical solution to the lateral earth pressure on a retaining wall for the cohesionless backfill with an inclined ground surface, based on the classical Rankine earth pressure theory. The graphical Mohr circle method has been used by many researchers to solve the soil-structure interaction problems in the horizontal or inclined ground condition (Richards Jr et al., 1990; Mazindrani and Ganjali, 1997; Iskander et al., 2013; Nian and Han, 2013). The research presented in this paper is a detailed analytical study on the upheaval buckling problem for shallow buried pipelines in the inclined ground condition. According

to the Terzaghi graphical solution method, the Rankine earth pressure theory, and the Mohr-Coulomb law, the uplift failure mechanism and the inclination angle of the slip surface are studied in detail. The impact of ground inclination on the peak uplift resistance is discussed. Finally, a simple equation considering the impact of ground inclination is proposed to predict the peak uplift resistance and validated by centrifuge experiments.

2 Stress state at a point in inclined ground

The Rankine earth pressure theory is widely adopted to solve the problem of soil-structure interactions (e.g. earth pressure on a retaining wall). Mazindrani and Ganjali (1997) analytically studied the lateral earth pressure problem with an inclined ground surface according to the Terzaghi graphical solution method and the stress equilibrium of a soil element. In this study, the Rankine earth pressure theory was used to investigate the upheaval buckling problem of a shallow buried pipeline. At any point on the slip surface in the inclined ground, the stress states of a soil element were derived using the Mohr circle graphic method.

Fig. 1a is a schematic of a buried pipeline within a cohesionless soil with ground inclination angle θ , effective unit weight γ' , and soil internal friction angle ϕ' . θ is smaller than ϕ' according to the Mohr-Coulomb law. Soil is assumed to be homogeneous and isotropic. The embedment depth H is the distance between the ground surface and the crown of the pipeline, and D is the diameter of the pipeline. In Fig. 1a, $abcd$ is a soil element at depth z on a potential slip surface, and planes ab and cd are parallel to the ground surface and the planes ad and bc are vertical. The vertical stress σ_v' acting on the plane ab is $\gamma'z \cdot \cos\theta$ (Mazindrani and Ganjali, 1997). σ_h' is the stress acting on planes ad and bc , and is parallel to the ground slope. According to the conjugate stress principle, stress planes ab and ad are conjugate planes, and the corresponding stresses σ_v' and σ_h' are termed as conjugate stresses.

In the initial state, the ground is under the at-rest stress condition. Once the pipeline starts to uplift, the stress conditions of the soil around the pipe begin to change (White et al., 2001). Bransby et al. (2001) pointed out that the peak uplift load is mobilized at a very small displacement of about $0.01D$. Therefore,

the plastic shear strain and the consequent slip surface occur when the uplift displacement of the pipeline is still very small. The whole soil block within the slip surfaces tends to be lifted with the pipeline. As the interaction between the soil on both sides of the potential slip surface reduces, the normal stress on that surface decreases. During pipeline uplifting, σ_v' is assumed to be constant while σ_h' gradually decreases until the soil element on the slip surface reaches the active limit equilibrium state, then soil begins to slip. The stress state of a soil element on the slip surface at that critical moment is analyzed based on the Rankine earth pressure theory.

According to the pole point method, the Mohr circle for soil element $abcd$ is shown in Fig. 1b. In the Mohr stress space (σ, τ), σ_1' and σ_3' are the maximum and minimum effective principal stresses for a soil element in the active state at the limit equilibrium, respectively. c' is the effective soil cohesion. Point A in Fig. 1b represents the vertical stress σ_v' on the face ab , which equals to l_{OA} , the length of OA . Thus,

$$\sigma_v' = l_{OA} = \gamma'z \cdot \cos \theta \tag{1}$$

σ_h' can be calculated according to the analysis elaborated in Appendix A:

$$\begin{aligned} \sigma_h' &= \left(\frac{2}{\gamma'z} J - 1 \right) \cdot \sigma_v' = \left(\frac{2}{\gamma'z} J - 1 \right) \cdot \gamma'z \cdot \cos \theta \\ &= 2J \cos \theta - \gamma'z \cdot \cos \theta, \end{aligned} \tag{2}$$

where $J = l_{OQ}$.

According to Eqs. (1) and (2), σ_v' and σ_h' can be predicted when the soil element reaches the active limiting equilibrium state. Consequently, the stress state on any planes within the soil element can be derived using the limit equilibrium method (Rao et al., 2016).

3 Derivation

3.1 Uplift mechanisms of a buried pipe for the horizontal ground condition

The sliding block theory, assuming that the soil block above the pipe bounded by a pair of shear bands uplifts as a whole, is widely used to predict the uplift resistance of a buried pipe. The curved slip surface is

normally assumed to be plane. The error induced by this simplification is negligible and the calculated results are therefore reasonable (Ghaly et al., 1991).

Trautmann et al. (1985) presented a review of uplift solutions for anchors and pipes. The most widely used mechanism is the vertical slip model. The vertical slip model assumes that failure occurs along a pair of straight slip planes initiating from the pipe waist, and extends to the ground surface (Fig. 2). The peak uplift resistance per unit length, R_{peak} , is defined as the sum of the weight of the overlying soil W and the friction on the slip surfaces $\int \tan \varphi' \cdot \sigma_h' dl$, where l is the length along the vertical slip surface. The lateral force σ_h' acting on the vertical failure plane is calculated by multiplying the vertical stress σ_v' by the lateral stress ratio K . This vertical slip model is widely used by engineers because of its simplicity. However, as some scholars have pointed out, there is a contradiction within the model. On the vertical failure plane, σ_h' is actually the minimum principal stress, so the shear stress on this plane ought to be zero (Handy, 1985). The model also assumes that the lateral earth pressure is in the at-rest condition; however, the stress condition changes during the uplift process (White et al., 2001).

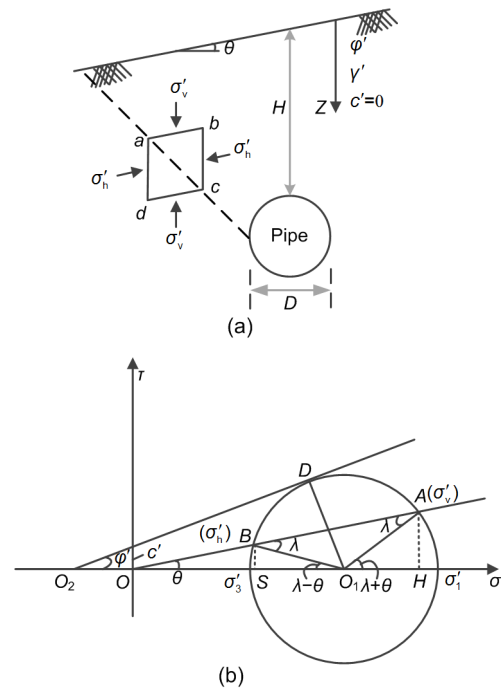


Fig. 1 Stress characteristics for soil around a pipeline in inclined ground

(a) Stress for soil element $abcd$; (b) The Mohr circle for soil element $abcd$

Recent experimental evidence revealed that the vertical slip-surface model was only approximate for uplift in loose sand at medium H/D ratios (Wang et al., 2012). For uplift in medium to dense sands, the failure mechanism is similar to that of the inclined slip surfaces model (Cheuk et al., 2008; Huang et al., 2015). The two symmetrical slip surfaces originate from the pipe waist with an inclination angle β to the vertical. Meyerhof and Adams (1968) stated that β varied between $\phi'/4$ and $\phi'/2$ for circular footings. Vermeer and Sutjiadi (1985) proposed that β was the same as the soil friction angle ϕ' . Chen et al. (2000) thought the failure angle was consistent with the Mohr-Coulomb failure criterion, and was equal to $45^\circ - \phi'/2$. White et al. (2001) observed from centrifuge tests that β was the dilation angle of sand.

It is clear that there are three problems with the existing methods for estimating the peak uplift resistance: (1) during pipe uplifting, the soil adjacent to the pipe is not in the at-rest condition, therefore, K_0 , the at-rest soil pressure parameter, is not suitable as the lateral earth pressure ratio; (2) there is paradox in the assumption of vertical slip model; (3) there are different understandings of the inclination angle β for the inclined slip surfaces model. The most common way of identifying β in recent research has been to use the particle image velocimetry (PIV) technique (Cheuk et al., 2008; Huang et al., 2015). However, β predicted by formulas do not match the test results well, and this discrepancy is wider for pipelines buried in the inclined ground.

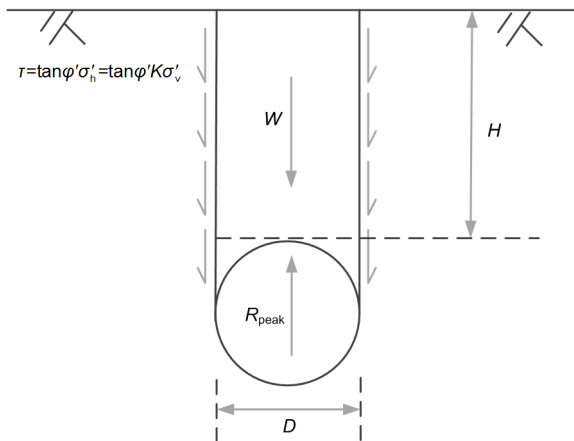


Fig. 2 Vertical slip-surface model

3.2 Analysis of the failure angle for a pipe uplifted in inclined ground

To build the numerical model, some assumptions were made: (1) the sliding block bounded by a pair of slip surfaces satisfied the sliding block theory; (2) soil within the slip surfaces transformed from the “at-rest” stress condition to the active limit equilibrium stress condition; (3) the two slip surfaces, originating from the pipe waist, were inclined at angles of α and β to the vertical on the right and left sides, respectively; (4) the soil satisfied the Rankine earth pressure theory and the Mohr-Coulomb failure criterion; (5) the lateral force on the pipe was not considered; (6) the contact friction between the smooth pipe and surrounding soil was negligible. The uplift resistance consists of the lifted soil wedge and the vertical component of shearing resistance along the two slip planes (Fig. 3).

3.2.1 Friction on the slip surfaces

A prism-shaped element adm (Fig. 4) is taken by slicing the soil element in Fig. 1 along line am parallel to the hypothetical failure plane, and along lines ad and dc (corresponding to planes ad and dm in Fig. 4, respectively). The normal stress and shear stress on plane am are denoted as σ'_β and τ'_β , respectively. l_{am} , l_{dm} , and l_{ad} are the corresponding side lengths. Therefore,

$$\frac{l_{am}}{\sin(90^\circ - \theta)} = \frac{l_{dm}}{\sin \beta} = \frac{l_{ad}}{\sin(90^\circ + \theta - \beta)}, \quad (3)$$

$$\sigma'_\beta \cdot l_{am} = \sigma'_v \cdot \sin \beta \cdot l_{dm} + \sigma'_h \cdot \cos(\beta - \theta) \cdot l_{ad}. \quad (4)$$

Assuming $l_{am}=1$ gives

$$l_{dm} = \frac{\sin \beta}{\cos \theta} \text{ and } l_{ad} = \frac{\cos(\theta - \beta)}{\cos \theta}. \quad (5)$$

Substituting Eqs. (5), (1), and (2) into Eq. (4) gives

$$\sigma'_\beta = \gamma' z \cdot \left\{ \sin^2 \beta - \cos^2(\beta - \theta) + \frac{2 \cos^2(\beta - \theta)}{\cos^2 \phi'} \right. \\ \left. \times \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \phi')} \right] \right\}. \quad (6)$$

According to the Mohr-Coulomb failure criterion for cohesionless soil, σ'_β and τ'_β should satisfy the relationship:

$$\tau'_\beta = \sigma'_\beta \cdot \tan \varphi'. \quad (7)$$

Similarly, the stresses σ'_α and τ'_α acting on the right failure plane are given as

$$\sigma'_\alpha = \gamma'z \left\{ \sin^2 \alpha - \cos^2(\theta + \alpha) + \frac{2 \cos^2(\theta + \alpha)}{\cos^2 \varphi'} \right. \quad (8)$$

$$\left. \times \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right] \right\},$$

$$\tau'_\alpha = \sigma'_\alpha \cdot \tan \varphi'. \quad (9)$$

By integrating the normal stress and the shear stress along both slip planes, the normal force and the shear force can be calculated as

$$N_\beta = \frac{1}{2} \cdot \frac{\left(-\frac{D}{2} \tan \theta + \frac{D}{2} + H \right)^2 \gamma'}{\tan \theta \sin \beta + \cos \beta} \cdot \left\{ \sin^2 \beta - \cos^2(\beta - \theta) \right. \quad (10)$$

$$\left. + \frac{2 \cos^2(\beta - \theta)}{\cos^2 \varphi'} \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right] \right\},$$

$$T_\beta = N_\beta \cdot \tan \varphi', \quad (11)$$

$$N_\alpha = \frac{1}{2} \cdot \frac{\left(\frac{D}{2} \tan \theta + \frac{D}{2} + H \right)^2 \gamma'}{\cos \alpha - \tan \theta \sin \alpha} \cdot \left\{ \sin^2 \alpha - \cos^2(\theta + \alpha) \right. \quad (12)$$

$$\left. + \frac{2 \cos^2(\theta + \alpha)}{\cos^2 \varphi'} \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right] \right\},$$

$$T_\alpha = N_\alpha \cdot \tan \varphi'. \quad (13)$$

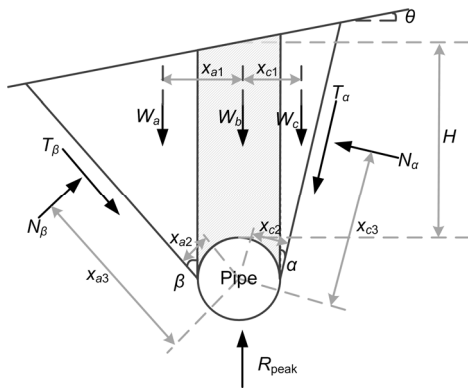


Fig. 3 Mechanical condition of a buried pipe for the inclined ground condition

Explanations of the variables are given in the following text

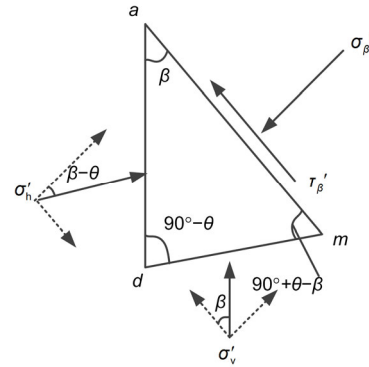


Fig. 4 Stress state of the soil element on the left failure plane

3.2.2 Self-weight of soil between the two slip planes

The uplifted soil block between the two slip planes can be divided into three components with self-weight per unit length of W_a , W_b , and W_c , respectively (Fig. 3).

$$W_a = \frac{1}{2} \cdot \frac{\gamma'HD}{\cot \beta + \tan \theta} \cdot \frac{D}{H} \cdot \left(\frac{H}{D} + 0.5 - 0.5 \tan \theta \right)^2, \quad (14)$$

$$W_b = \left[1 + \left(0.5 - \frac{\pi}{8} \right) \frac{D}{H} \right] \cdot \gamma'HD, \quad (15)$$

$$W_c = \frac{1}{2} \cdot \frac{\gamma'HD}{\cot \alpha - \tan \theta} \cdot \frac{D}{H} \cdot \left(\frac{H}{D} + 0.5 + 0.5 \tan \theta \right)^2. \quad (16)$$

3.2.3 Failure plane angles and the peak uplift resistance

The stress condition around the pipeline at the critical state is illustrated in Fig. 3. The forces act on the sliding block are the weight of the soil, $W_a + W_b + W_c$, the normal forces, N_β and N_α , and the shear forces, T_β and T_α . All the forces mentioned above should satisfy the balance of force and moment,

$$\text{that is, } \begin{cases} \sum M = 0, \\ \sum F_x = 0, \text{ as} \\ \sum F_y = 0, \end{cases}$$

$$W_a \cdot x_{a1} + T_\beta \cdot x_{a2} - N_\beta \cdot x_{a3} \quad (17)$$

$$= W_c \cdot x_{c1} + T_\alpha \cdot x_{c2} - N_\alpha \cdot x_{c3},$$

$$T_\beta \sin \beta + N_\beta \cos \beta = T_\alpha \sin \alpha + N_\alpha \cos \alpha, \quad (18)$$

$$R_{\text{peak}} = W_a + W_b + W_c + (T_\beta \cos \beta - N_\beta \sin \beta) \quad (19)$$

$$+ (T_\alpha \cos \alpha - N_\alpha \sin \alpha),$$

where

$$x_{a1} = \frac{\frac{D}{2} + H - \frac{\tan \theta \cdot D}{2}}{3(\tan \theta + \cot \beta)} + \frac{D}{2}; \quad x_{a2} = \frac{\cos \beta \cdot D}{2};$$

$$x_{a3} = \frac{-\frac{\tan \theta \cdot D}{2} + \frac{D}{2} + H}{3(\tan \theta \sin \beta + \cos \beta)} + \frac{\sin \beta \cdot D}{2};$$

$$x_{c1} = \frac{\frac{D}{2} + H + \frac{\tan \theta \cdot D}{2}}{3(\cot \alpha - \tan \theta)} + \frac{D}{2}; \quad x_{c2} = \frac{\cos \alpha \cdot D}{2};$$

$$x_{c3} = \frac{\frac{\tan \theta \cdot D}{2} + \frac{D}{2} + H}{3(\cos \alpha - \tan \theta \sin \alpha)} + \frac{\sin \alpha \cdot D}{2}.$$

Substituting Eqs. (10)–(16) into Eq. (19), the expression for peak soil resistance is

$$R_{\text{peak}} = \left[1 + \left(0.5 - \frac{\pi}{8} \right) \frac{D}{H} \right] \cdot \gamma' HD$$

$$+ \frac{\left(-\frac{D}{2} \tan \theta + \frac{D}{2} + H \right)^2 \gamma' \tan \beta + (\tan \varphi' - \tan \beta) \cdot M_a}{2 \tan \theta \tan \beta + 1}$$

$$+ \frac{\left(\frac{D}{2} \tan \theta + \frac{D}{2} + H \right)^2 \gamma' \tan \alpha + (\tan \varphi' - \tan \alpha) \cdot M_c}{2 \cdot 1 - \tan \theta \tan \alpha}, \quad (20)$$

where M_a and M_c are intermediate variables,

$$M_a = \sin^2 \beta - \cos^2(\beta - \theta)$$

$$+ \frac{2 \cos^2(\beta - \theta)}{\cos^2 \varphi'} \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right];$$

$$M_c = \sin^2 \alpha - \cos^2(\theta + \alpha)$$

$$+ \frac{2 \cos^2(\theta + \alpha)}{\cos^2 \varphi'} \left[\cos^2 \theta - \sqrt{\cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right].$$

When the inclination angle of the ground surface θ is equal to zero, the slip surfaces on the left and right are symmetrical and $\beta = \alpha$. Eq. (19) transfers to:

$$R_{\text{peak}} = \left[1 + \left(0.5 - \frac{\pi}{8} \right) \frac{D}{H} \right] \cdot \gamma' HD + \left(\frac{D}{2} + H \right)^2 \gamma' \cdot \tan \beta$$

$$+ \left(\frac{D}{2} + H \right)^2 \gamma' \cdot (\tan \varphi' - \tan \beta) \cdot \left(\frac{1 + K_a}{2} - \frac{1 - K_a}{2} \cos(2\beta) \right),$$

$$K_a = \tan^2 \left(45^\circ - \frac{\varphi'}{2} \right). \quad (21)$$

According to Eqs. (20) and (21), the peak uplift resistance is a function of the failure plane angles α and β , the ground inclination angle θ , the effective unit weight γ' , the peak internal friction angle φ' , and the embedment ratio H/D . Combining Eq. (17) with Eq. (18) yields Eq. (22), which is given at the end of the page.

In Eq. (22), α and β are the functions of ground inclination angle θ , the peak internal friction angle φ' , and the embedment ratio H/D . Eq. (22) is a transcendental equation, as the analytical solution is difficult to obtain.

4 Slip surface angles

4.1 Inclination angle of the slip surface for the horizontal ground condition

Eq. (22) cannot directly solve the problem of the horizontal ground surface condition where $\theta = 0^\circ$ and $\alpha = \beta$. To predict α and β in the horizontal ground condition, θ is simplified as 0.1° . Fig. 5 shows the impact of φ' and H/D on the inclination angles of the

$$\left\{ \begin{array}{l} \left(-0.5 \tan \theta + 0.5 + \frac{H}{D} \right)^2 \frac{1 + (\tan \varphi' \cot \beta - 1) \cdot M_a + \frac{1 + \frac{2H}{D} - \tan \theta}{3(\cot \beta + \tan \theta)^2} \left(1 - \frac{M_a}{\sin^2 \beta} \right)}{\tan \theta + \cot \beta} = 1, \\ \left(0.5 \tan \theta + 0.5 + \frac{H}{D} \right)^2 \frac{1 + (\tan \varphi' \cdot \cot \alpha - 1) M_c + \frac{1 + \frac{2H}{D} + \tan \theta}{3(\cot \alpha - \tan \theta)^2} \left(1 - \frac{M_c}{\sin^2 \alpha} \right)}{\cot \alpha - \tan \theta} \\ \left(-0.5 \tan \theta + 0.5 + \frac{H}{D} \right)^2 \frac{\tan \varphi' + \cot \beta}{\tan \theta + \cot \beta} \cdot \frac{\cot \alpha - \tan \theta}{\cot \alpha + \tan \varphi'} \frac{M_a}{M_c} = 1. \\ \left(0.5 \tan \theta + 0.5 + \frac{H}{D} \right)^2 \end{array} \right. \quad (22)$$

slip surfaces. As H/D increases from 0.1 to 8, there is a significant increase in the failure angle. This is because the lateral constraint pressure increases with the increasing H/D . Therefore, soil could dilate more easily at a shallower depth, resulting in a steeper slip surface, as observed by Cheuk et al. (2008) and Huang et al. (2015). The failure angle increases as φ' decreases. For a given φ' , the curves gradually approach the value of $45^\circ - \varphi'/2$ with H/D further increasing from 8 to 80, which confirms the Rankine earth pressure theory and the Mohr-Coulomb failure criterion.

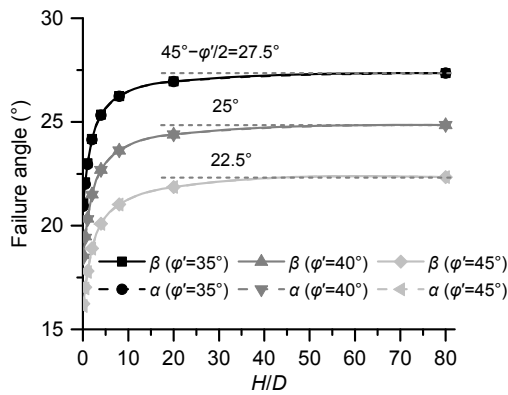


Fig. 5 Failure angles of the slip surface versus the embedment ratio H/D for the horizontal ground condition

4.2 Inclination angle of the slip surface for the inclined ground condition

Under the inclined ground condition, Fig. 6 shows the impact of θ and H/D on the failure angles with a constant soil internal friction angle φ' of 35° based on Eq. (22). α on the uphill side is depicted by dashed lines, and β on the downhill side by solid lines. The two slip surfaces are no longer symmetric and α is not equal to β . α becomes smaller and β becomes larger as θ increases. The two slip surfaces rotate towards the downhill direction (Fig. 7), and the variation of β is larger than that of α . Comparing with the horizontal ground condition, at any specific embedment ratio H/D , the change in α and β increases as θ increases (Fig. 6). When H/D is 0.1, α gradually approaches 0 with the increasing θ to the upper bound value of about 23° ; for the embedment ratio $H/D=2$, the upper bound θ in Eq. (22) is about 33° . The variation of α and β with H/D is further depicted in Fig. 8. For $\theta=20^\circ$, α and β are significantly impacted by the embedment ratio when $H/D < 4$; however, H/D has a

negligible effect on α and β when H/D increases from 4 to 8, and the curve of α for $\theta=20^\circ$ gradually coincides with that for $\theta=0.1^\circ$. The difference between α and β decreases with the growing H/D . At higher embedment ratios like $H/D=8$, the effect of the ground surface inclination is negligible and the two slip planes during pipeline uplifting can be simplified as symmetric.

Due to the existence of initial shear stress, an underground structure buried in inclined ground is subjected to a horizontal force (Zhu and Randolph, 2010), especially when the ground inclination is close to the soil friction angle φ' . The failure angles of β for the variation of θ when $H/D=20$ are plotted in Fig. 9. There is a significant increase in the gradient of the curves when θ is approximately equal to $\varphi' - 10^\circ$. When the slope angle θ approaches the soil friction angle φ' , the slope is prone to be unstable; therefore, the pipe under the slope is subject to an increasing downslope force. The horizontal force component of the downslope force is no longer negligible, which contradicts the assumption that the horizontal force on the pipe is negligible. Thus, all the analysis above, derived using the proposed analytical formula, is applicable for the condition that $\theta < \varphi' - 10^\circ$.

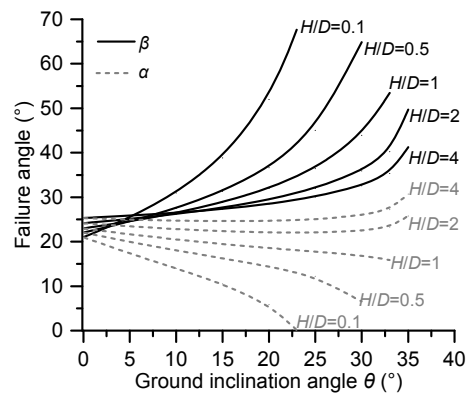


Fig. 6 Failure angles of the slip surface versus the ground inclination θ ($\varphi'=35^\circ$)

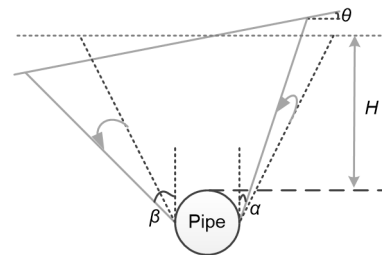


Fig. 7 Uplift failure mechanism for the inclined ground condition

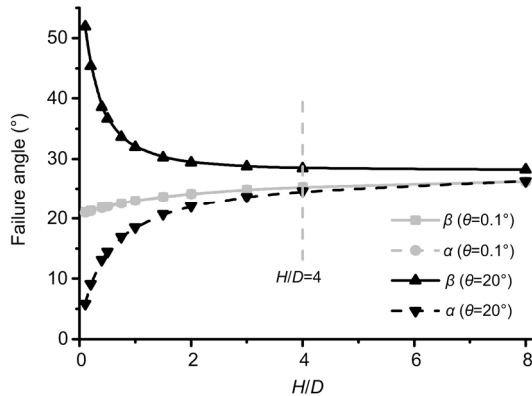


Fig. 8 Failure angles of the slip surface versus the embedment ratio H/D for the inclined ground condition

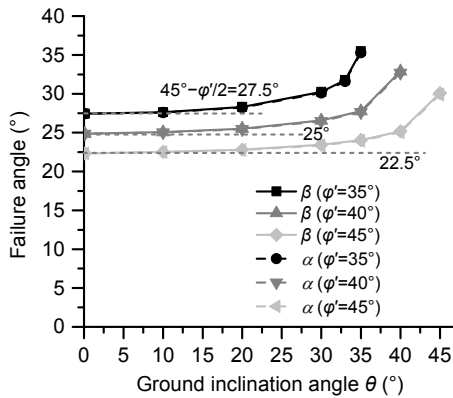


Fig. 9 Failure angles of the slip surface at $H/D=20$ for the inclined ground condition

4.3 Design chart for slip surface angles

Fig. 10 reveals the variation of failure angles with H/D and θ under internal friction angles ϕ' of 35° , 40° , and 45° , respectively. Based on the analysis, failure angles are influenced by ϕ' , θ , and H/D , particularly for shallow burial conditions. There is a slight decrease in α and β with the increasing ϕ' . Compared with the horizontal ground condition, the impact of ground inclination on failure angles decreases with the increasing H/D . Prediction of peak uplift resistance using Eq. (20) requires knowledge of both α and β . Therefore, Fig. 10 provides a direct engineering reference for designers.

5 Peak soil resistance

The peak uplift resistance of a buried pipe in horizontal ground has historically been expressed in

the normalized form as (DNV, 2007)

$$\frac{R_{\text{peak}}}{\gamma'HD} = 1 + \left(0.5 - \frac{\pi}{8}\right) \frac{D}{H} + f_d \cdot \left[\frac{D}{H} \cdot \left(\frac{H}{D} + 0.5\right)\right]^2, \tag{23}$$

where f_d is the uplift resistance factor, which depends on soil properties and slip surface modes (vertical and inclined). Proper estimation of the uplift resistance factor f_d for pipeline design is important in preventing the upheaval buckling and reducing the investment. Many aspects regarding this factor have been discussed, including soil classification and soil density (Trautmann et al., 1985; DNV, 2007).

For the inclined ground condition, the peak uplift resistance expressed in Eq. (20) is normalized by $\gamma'HD$ from both sides of the equation. The normalized form $R_{\text{peak}}/(\gamma'HD)$ can also be expressed by Eq. (23). To distinguish the inclined ground condition from the horizontal ground condition, the dimensionless uplift resistance factor f_d is replaced by f_d' as

$$f_d' = \frac{1}{2} \cdot \frac{\tan \beta + (\tan \phi' - \tan \beta) \cdot M_a}{\tan \theta \tan \beta + 1} \cdot \left(1 - \frac{\tan \theta \cdot D}{2H_c}\right)^2 + \frac{1}{2} \cdot \frac{\tan \alpha + (\tan \phi' - \tan \alpha) \cdot M_c}{1 - \tan \theta \tan \alpha} \cdot \left(1 + \frac{\tan \theta \cdot D}{2H_c}\right)^2, \tag{24}$$

where $H_c = H + 0.5D$ is the buried depth to the centre of the pipe. The factor f_d' is a function of ϕ' , H/D , θ , and the failure plane angles α and β .

Based on the above analysis of the slip surface angles and Eq. (24), the normalized form f_d' versus θ is plotted in Fig. 11 (p.378). For $H/D=1$, f_d' is almost constant at 0.53 with the variation of θ from 0.1° to 25° , despite the difference of failure angles. However, f_d' decreases significantly with the increasing θ when $H/D=0.5$, especially when θ is between 15° and 25° . Fig. 12 (p.378) shows the relationship between f_d' (f_d) and H/D under various ground inclinations θ . For a specific θ , f_d' first increases significantly with the increasing H/D when H/D is less than 1, then gradually reaches a constant value when H/D is larger than 4. This is because the impact of θ on α and β is negligible when $H/D \geq 4$ (Fig. 8). According to Fig. 12,

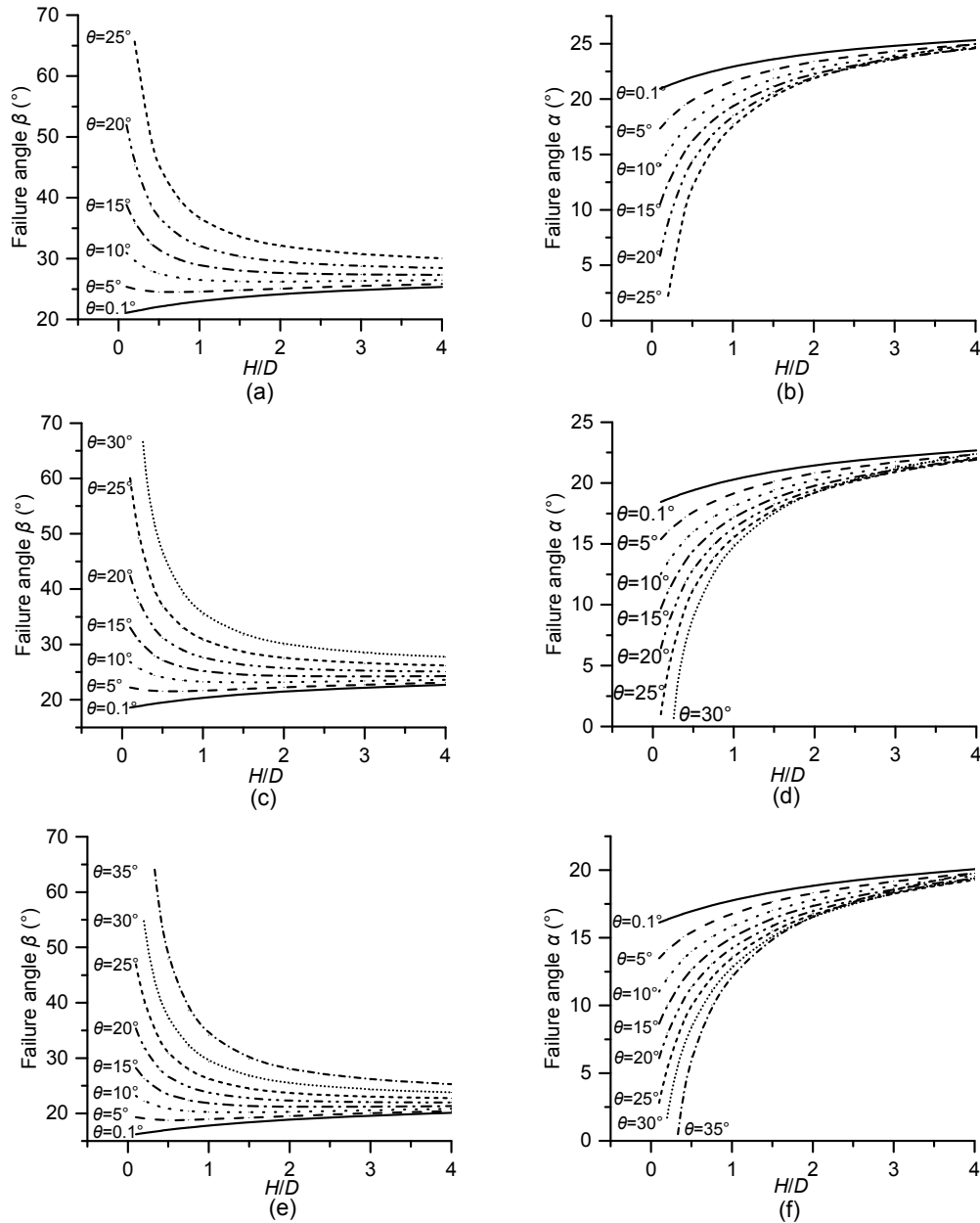


Fig. 10 Design chart for the failure angles

(a) Failure angle β ($\varphi'=35^\circ$); (b) Failure angle α ($\varphi'=35^\circ$); (c) Failure angle β ($\varphi'=40^\circ$); (d) Failure angle α ($\varphi'=40^\circ$); (e) Failure angle β ($\varphi'=45^\circ$); (f) Failure angle α ($\varphi'=45^\circ$)

there is no significant difference between f_d' and f_d when $H/D \geq 1$. The calculated f_d' in this study is close to the results of Vermeer and Sutjiadi (1985) and between the upper and lower bounds of the DNV method. For $H/D < 1$, f_d' decreases significantly with the increasing θ . When $\theta \geq 15^\circ$, f_d' under shallow burial conditions (e.g. $H/D < 0.5$) is smaller than the lower bound value recommended by DNV (2007), resulting in an inadequate uplift resistance and the potential for

upheaval buckling. Therefore, sufficient burial depth is essential during the pipeline installation, especially for the inclined ground condition. However, burial depth is one of the main sources of installation cost and is largely limited by the budget. Inadequate burial depth is one of the reasons why the upheaval buckling phenomenon generally occurs in sloping regions.

The present design codes for petroleum and natural gas pipelines do not consider the influence of

ground inclination on peak uplift resistance. For some regulations (e.g. ISO (2017) and DEP 31.40.00.10), the minimum pipeline embedment depth is 0.5 m. Pipelines for oil and gas transportation normally have a diameter of 1–2 m, and the corresponding minimum burial ratio H/D is less than 0.5. According to Figs. 11 and 12, the safety factor decreases due to the ground inclination under this “very shallow” burial condition. To illustrate the impact of ground inclination on peak uplift resistance under the shallow burial condition ($H/D < 1$), a reduction factor $k_{\text{incline}} = f'_d / f_d$ is introduced as

$$k_{\text{incline}} = \left(\frac{\frac{H}{D}}{6 + 29 \cdot \frac{H}{D}} - 0.0285 \right) \cdot 12 \cdot \frac{(\theta - 2^\circ)^2}{(\varphi' - 20^\circ)^2} + 1, \quad (25)$$

$$f'_d = \begin{cases} k_{\text{incline}} \cdot f_d, & \frac{H}{D} < 1, \\ f_d, & \frac{H}{D} \geq 1. \end{cases} \quad (26)$$

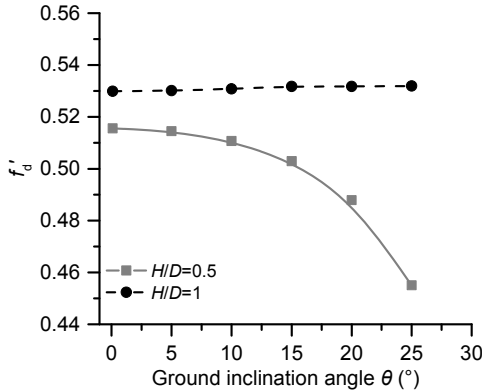


Fig. 11 f'_d versus θ ($\varphi'=35^\circ$)

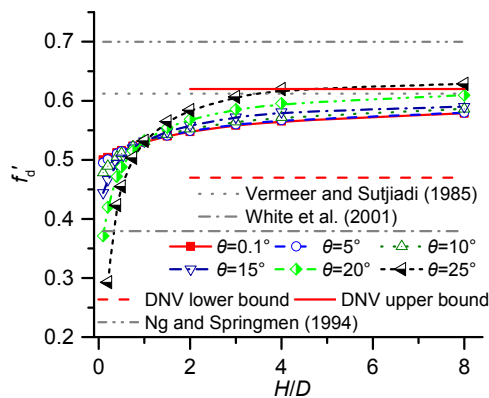


Fig. 12 f'_d versus H/D ($\varphi'=35^\circ$)

Calculating the value of f'_d by Eqs. (25) and (26), then replacing f_d with f'_d in Eq. (23), the peak uplift resistance of a pipe buried in the inclined ground condition can be predicted.

6 Experimental validation

Centrifuge modelling has been widely adopted to study soil-structure interactions due to the high cost and labour associated with full-scale tests. These centrifuge tests use the scaled models and increase the body stresses by centrifugal acceleration. The experiments presented here were carried out at an acceleration level of 30g, where g is the gravitational acceleration, using the ZJU-400 centrifuge at Zhejiang University, China (Chen et al., 2010). The model pipe was made from a hollow aluminum tube with an external diameter, D , of 40 mm and wall thickness of 2 mm. The material used in the tests was classified as poorly graded sand. The diameters of the sand particles at which 10%, 30%, and 60% by mass are finer were 0.11, 0.14, and 0.19 mm, respectively. Medium dense samples with the targeted relative density, I_D , of 60% were prepared by dry pluviation. Shear tests on eight specimens revealed that the sand had a peak state friction angle of around 42° . The tests were divided into three series with the ground sloping, θ , of 0° , 10° , and 20° , respectively. The depth of the pipe crown, H , varied between $0.5D$ and $4D$ to simulate the shallowly buried pipelines. Digital images were captured and PIV technique was used to track the soil movement. Details of the experiment were described by Liu (2017).

Fig. 13 shows the variation of tested failure angles with H/D . With the increasing H/D , β declines and α rises, showing the decreasing impact of ground inclination on the rotation of the two failure planes, as depicted in Figs. 8 and 10. Under the same H/D , β increases and α decreases with a higher θ . Although the experimental β is relatively higher and α is smaller than the corresponding analytical prediction, the difference of $R_{\text{peak}}/(\gamma'HD)$ between the analytical and experimental results is within 6% (Fig. 14). Therefore, the upheaval buckling problem of a shallow buried pipeline in inclined cohesionless soil can be well-predicted according to the proposed analytical method.

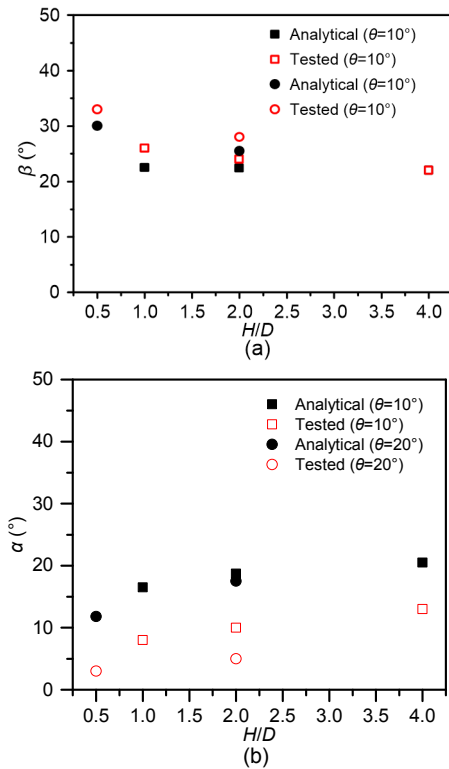


Fig. 13 Comparison of failure angles of β (a) and α (b)

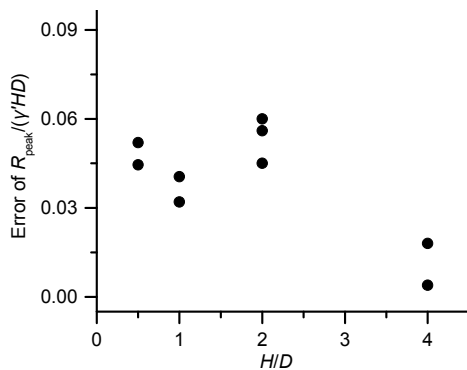


Fig. 14 Comparison of $R_{peak}/(\gamma'HD)$ between analytical and experimental results

$$\text{Error} = (|\text{Analytical result} - \text{Test result}|) / \text{Analytical result}$$

7 Conclusions

The upheaval buckling problem of shallow buried pipelines in inclined cohesionless soil was studied analytically. According to the Rankine earth pressure theory and Mohr-Coulomb failure criterion, the failure angles for an uplifted pipe were discussed in detail. An equation for predicting the peak uplift resistance

of a buried pipe under an inclined ground condition was proposed and its simplified form was presented for the designers. Finally, the analytical method was validated by centrifuge experiments. Based on the analysis, the following conclusions were reached:

The inclinations of failure plane angles are not the same for the inclined ground condition. The two failure planes rotate in the downhill direction. The area of soil bounded by two slip surfaces for inclined ground is larger than that in horizontal ground. The magnitude of rotation increases with the increasing ground inclination θ for a given embedment ratio H/D , and decreases with the increasing H/D for a given θ . When H/D is larger than 4, the influence of the ground slope is negligible.

The peak uplift resistance reduces in inclined ground, especially when H/D is less than 1. The relevant design codes do not consider the impact of ground inclination on the uplift resistance, resulting in a decrease in the safety factor.

Contributors

Bo HUANG and Dao-sheng LING designed the research. Jing-wen LIU and Ji-ying FAN did the theoretical derivation and wrote the first draft of the manuscript. Bo HUANG and Ji-ying FAN helped to organize the manuscript, and revised and edited the final version.

Conflict of interest

Bo HUANG, Jing-wen LIU, Ji-ying FAN, and Dao-sheng LING declare that they have no conflict of interest.

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Appendix A: derivation of σ_h'

The stress acting on plane ad (σ_h') is equal to the length of OB , that is l_{OB} (Fig. 1). The coordinates of point A are

$$l_{OH} = \gamma'z \cdot \cos^2 \theta, \tag{A1}$$

$$l_{AH} = \gamma'z \cdot \cos \theta \cdot \sin \theta. \tag{A2}$$

Based on the geometrical relationship in Fig. 1b,

$$\frac{\sigma'_h}{\sigma'_v} = \frac{l_{OB}}{l_{OA}} = \frac{l_{BS}}{l_{AH}} = \frac{\sin(\lambda - \theta)}{\sin(\lambda + \theta)} = \frac{\cos \theta - \sin \theta \cdot \cot \lambda}{\cos \theta + \sin \theta \cdot \cot \lambda}. \tag{A3}$$

Let $J = l_{OQ_1}$, then

$$\tan(\lambda + \theta) = \frac{l_{AH}}{l_{OAH}} = \frac{\gamma'z \cdot \cos \theta \cdot \sin \theta}{\gamma'z \cdot \cos^2 \theta - J}, \tag{A4}$$

and

$$\cot \lambda = \left(\frac{\gamma'z}{J} - 1 \right) \cot \theta. \tag{A5}$$

Substituting Eq. (A5) into Eq. (A3) gives

$$\begin{aligned} \frac{\sigma'_h}{\sigma'_v} &= \frac{\cos \theta - \sin \theta \cdot \left(\frac{\gamma'z}{J} - 1 \right) \cot \theta}{\cos \theta + \sin \theta \cdot \left(\frac{\gamma'z}{J} - 1 \right) \cot \theta} \\ &= \frac{1 - \left(\frac{\gamma'z}{J} - 1 \right)}{1 + \left(\frac{\gamma'z}{J} - 1 \right)} = \frac{2}{\gamma'z} J - 1. \end{aligned} \tag{A6}$$

At the limit equilibrium state, the Mohr circle is tangential to the Mohr-Coulomb yield envelope O_2D at point D as shown in Fig. 1b. Therefore,

$$R = l_{O,D} = (c' \cdot \cot \varphi' + J) \cdot \sin \varphi' = c' \cdot \cos \varphi' + J \cdot \sin \varphi', \tag{A7}$$

$$R^2 = l_{O,A}^2 = l_{O,H}^2 + l_{AH}^2 = (\gamma'z \cdot \cos^2 \theta - J)^2 + (\gamma'z \cdot \cos \theta \cdot \sin \theta)^2, \tag{A8}$$

$$\begin{aligned} &(\gamma'z \cdot \cos^2 \theta - J)^2 + (\gamma'z \cdot \cos \theta \cdot \sin \theta)^2 \\ &= (c' \cdot \cos \varphi' + J \cdot \sin \varphi')^2, \end{aligned} \tag{A9}$$

where R is the radius of the Mohr circle. For the cohesionless soil, $c'=0$, J can be simplified as

$$\begin{aligned} J &= \frac{1}{\cos^2 \varphi'} \\ &\times \left[\gamma'z \cdot \cos^2 \theta - \sqrt{(\gamma'z)^2 \cdot \cos^2 \theta \cdot (\cos^2 \theta - \cos^2 \varphi')} \right]. \end{aligned} \tag{A10}$$

σ'_h is calculated by substituting Eq. (A10) into Eq. (A6):

$$\begin{aligned} \sigma'_h &= \left(\frac{2}{\gamma'z} J - 1 \right) \cdot \sigma'_v = \left(\frac{2}{\gamma'z} J - 1 \right) \cdot \gamma'z \cdot \cos \theta \\ &= 2J \cos \theta - \gamma'z \cdot \cos \theta. \end{aligned} \tag{A11}$$