# Multi-actuated mechanism design considering structure flexibility using correlated performance reinforcing 

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## Multi-actuated mechanism



1-Wiring terminal; 2-Deion plates for arc extinguishing; 3-Upper moulded case; 4-Moving contactor K; 5-Fixed joint in moving contactor; 6-Revolute joint D; 7-One end J of main spring JB; 8-Manual Operating Handle JB; 9—Revolute joint C/ Ground; 10—Jump buckle; 11—Upper linkage BD; 12—Revolute joint O/Ground;13—Revolute joint B; 14—High contact joint T/ Latch buckle TH; 15—Drawbar spring; 16-Thermo-pretightening regulator; 17-Cantilevered thermobimetallic strip; 18-Flapped electromagnet armature; 19-Shortlong time delay tripping trigger; 20-Revolute joint H/Ground; 21-Instantaneous tripping trigger; 22-Moving contactor spring; 23-Revolute joint R of main shaft/Ground; 24-Revolute joint A; 25-Lower linkage BA; 26-Static contactor; 27-Fastening bolt; 28-Lower moulded case; 29-Conductor terminal.

Fig. 2 (a) Cutaway view of rigid-flexible multi-body dynamics mechanism

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## Multi-actuated mechanism



Fig. 2 (b) Isometric drawing of rigid-flexible multi-body dynamics mechanism

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## Displacement, velocity, acceleration, force and torque by correlated performance reinforcing



Fig. 4 Displacement, velocity, acceleration, force and torque on $K$ by correlated performance reinforcing

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## Conclusions

■ A multi-actuated mechanism design method considering structure flexibility using correlated performance reinforcing is put forward.

- Simulation showed that the structure flexibility can reduce the tripping velocity, which is non-negligible, especially for high frequency tripping.
- The experimental results were in agreement with the simulation results in terms of the relative extent to which the key structures in temperature rising.

